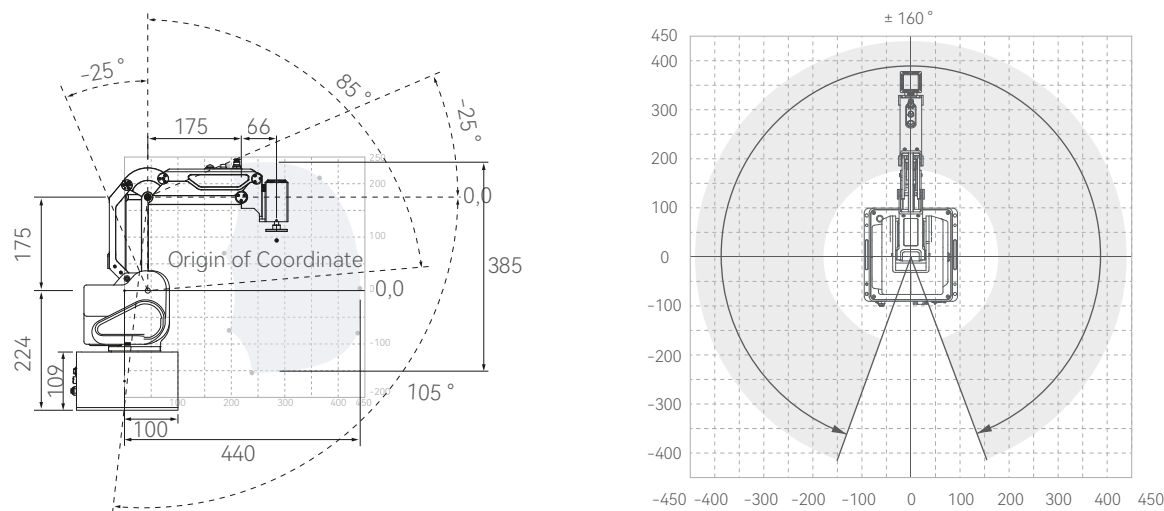


Product Specifications



|                          |                                    |               |
|--------------------------|------------------------------------|---------------|
| Model                    | MG400                              |               |
| Number of Axes           | 4                                  |               |
| Payload                  | 500 g (Max 750 g)                  |               |
| Working Radius           | 440 mm                             |               |
| Repeatability            | ±0.05 mm                           |               |
| Range of Motion          | J1                                 | ±160°         |
|                          | J2                                 | -25° to 85°   |
|                          | J3                                 | -25° to 105°  |
|                          | J4                                 | -360° to 360° |
| Maximum Joint Speed      | J1                                 | 300°/s        |
|                          | J2                                 | 300°/s        |
|                          | J3                                 | 300°/s        |
|                          | J4                                 | 300°/s        |
| Power                    | 100 to 240V AC, 50/60 Hz           |               |
| Rated Voltage            | 48V DC                             |               |
| Power Consumption        | J1: 75W, J2: 50W, J3: 50W, J4: 30W |               |
| Communication Interface  | TCP/IP, Modbus TCP                 |               |
| Installation Orientation | Desktop                            |               |
| Weight                   | 8 kg                               |               |
| Base Dimensions          | 190 mm × 190 mm                    |               |
| Working Environment      | 0° to 40° C                        |               |
| Software                 | DobotStudio Pro, SCStudio          |               |

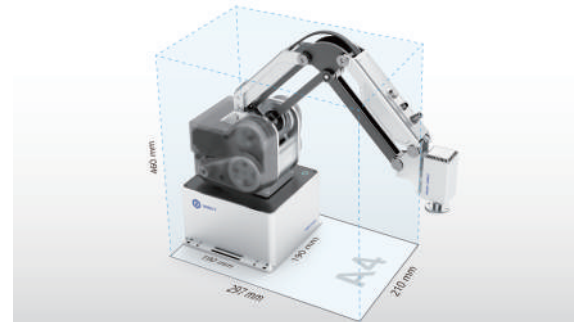


# DOBOT MG400

The MG400 is a lightweight desktop grade robotic arm with a footprint smaller than a piece of A4 paper. Designed to be flexible to deploy, easy to use, and safe to collaborate, the MG400 makes automation affordable and accessible for diversified and small-batch production scenarios. Featuring 750 g payload, 440 mm maximum reach, drag-to-teach and collision detection, the MG400 is perfect for lightweight desktop applications and fast deployment into production lines.

## Desktop Grade Compact

The MG400 has a compact design that integrates the control box into the machine body with just 190 mm x 190 mm footprint to be easily integrated into any production environment. Any space that fits a piece of A4 paper, the MG400 is good to go.



## Industrial Grade Performance

The MG400 is equipped with servo motors with a high-precision absolute encoder, a proprietary servo drive and controller, achieving a repeatability of  $\pm 0.05$  mm.

With the vibration suppression algorithm deployed at the controller level, under the condition of ensuring the space trajectory accuracy of the robot's multi-axis motion, the repeatability bandwidth stabilization time is accelerated by 60%, and the residual vibration is reduced by 70%.



## Simplicity Means Productivity

The design concept of simplicity is integrated into every dimension of the robot, making it much easier for small and medium-sized enterprises to start automation.

### Shorter Deployment Time.

Integrated and compact design with plug-and-play accessories, the MG400 is flexible and easy to deploy.



Step 1



Step 2



Step 3



Step 4

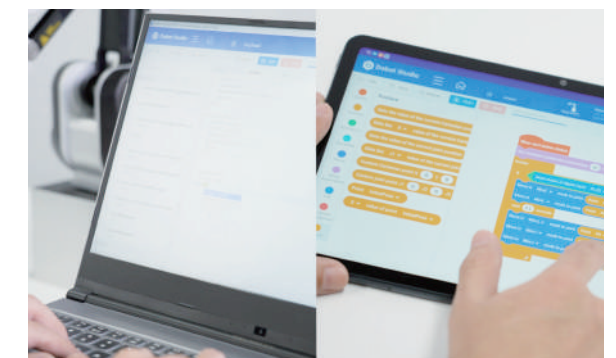
### More Programming Options.

With drag-to-teach, graphical programming, and Lua script programming, operators of different levels of programming skills can easily master the MG400.



### Higher Programming Efficiency.

Intuitive programming interface and guided-interactive design greatly improve the programming efficiency and lower the threshold of robotics applications.



### Higher Debugging Efficiency.

Supported by the robot dynamicgravity compensation algorithm, the MG400 hand-held teaching is smooth, easy and efficient, reducing the teaching time during robot programming by up to 80%.

